

# VDL Steelweld

Meet gereedschap Quality Control





## 3x Vantage mobile Laser tracker systems



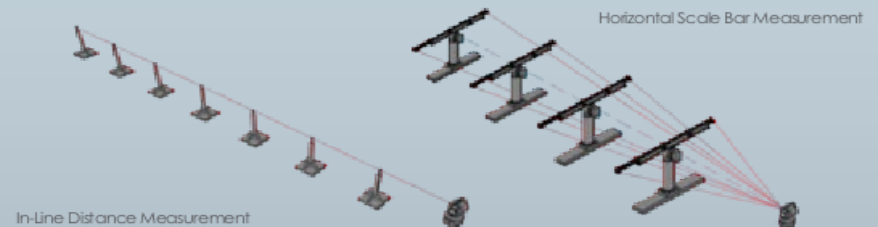
laser tracker technology

FARO Vantage

### Point to Point Accuracy\*\*\*

In-Line Distance Measurement							
Length	2-5m (6.6-16.4ft)	2-10m (6.6-32.8ft)	2-20m (6.6-65.6ft)	2-30m (6.6-98.4ft)	2-40m (6.6-131.2ft)	2-60m (6.6-196.9ft)	2-80*m (6.6-262.5ft)
Distance	3m (9.8ft)	8m (26.2ft)	18m (59ft)	28m (91.9ft)	38m (124.7ft)	58m (190.3ft)	78m (255.9ft)
ADM	MPE	0.018mm (0.0007")	0.022mm (0.0009")	0.030mm (0.0012")	0.038mm (0.0015")	0.046mm (0.0018")	0.078mm (0.0031")
	Typical	0.009mm (0.0004")	0.011mm (0.0004")	0.015mm (0.0006")	0.019mm (0.0008")	0.023mm (0.0009")	0.031mm (0.0012")

\*With selected targets. \*\*Product complies with radiation performance standards under the food, drug, and cosmetics act and international standard EC 60825-1 2001-08. \*\*\*MPE and all accuracy specifications are calculated per ASME B89.4.19 - 2006. Variation in air temperature is not included. Specifications, descriptions, and technical data may be subject to change. \*\*\*\*With integrated weather station. Protected by U.S. patents: 7,327,446 7,352,446 7,466,401 7,701,559 8,040,525 8,120,780



Horizontal Scale Bar Measurement (2.3m, 7.55ft)									
Range	2m (6.6ft)	5m (16.4ft)	10m (32.8ft)	20m (65.6ft)	30m (98.4ft)	40m (131.2ft)	60m (196.9ft)	80*m (262.5ft)	
ADM	MPE	0.044mm (0.0017")	0.064mm (0.0025")	0.099mm (0.0039")	0.170mm (0.0067")	0.240mm (0.0095")	0.311mm (0.0122")	0.453mm (0.0178")	0.594mm (0.0234")
	Typical	0.022mm (0.0009")	0.032mm (0.0013")	0.049mm (0.0019")	0.085mm (0.0033")	0.120mm (0.0047")	0.156mm (0.0061")	0.226mm (0.0089")	0.297mm (0.0117")



1x ION mobile Laser tracker system

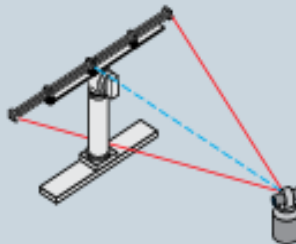


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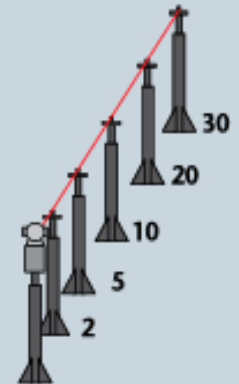
## FARO Laser Tracker ION™

### Point-to-Point Typical Accuracy\*\*\*

Horizontal Scale Bar Measurement (2.3 m)		
Range (m)	ADM (mm)	IFM (mm)
2	0.022	0.021
5	0.032	0.032
10	0.049	0.049
20	0.085	0.085
30	0.120	0.120
40	0.156	0.156
50*	0.191	0.191
55*	0.209	0.209



In-Line Distance Measurement			
Length (m)	Distance (m)	ADM (mm)	IFM (mm)
2 - 5	3	0.009	0.003
2 - 10	8	0.011	0.005
2 - 20	18	0.015	0.009
2 - 30	28	0.019	0.013
2 - 40	38	0.023	0.017
2 - 50*	48	0.027	0.021
2 - 55*	53	0.029	0.023





## 1x Focus mobile Laser Scanner system

### Laser Scanner Focus<sup>3D</sup> X 130



#### Performance Specifications Focus<sup>3D</sup> X 130

##### Ranging unit

Unambiguity interval: >130m  
 Range Focus<sup>3D</sup> X 130: 0.6m - 130m indoor or outdoor with upright incidence to a 90% reflective surface  
 Measurement speed (pts/sec): 122,000 / 244,000 / 488,000 / 976,000  
 Ranging error<sup>1</sup>: ±2mm

Ranging noise <sup>2</sup>	@10m	@10m - noise compressed <sup>3</sup>	@25m	@25m - noise compressed <sup>3</sup>
@ 90% refl.	0.3mm	0.15mm	0.3mm	0.15mm
@ 10% refl.	0.4mm	0.2mm	0.5mm	0.25mm

##### Colour unit

Resolution: Up to 70 megapixel colour  
 Dynamic colour feature: Automatic adaption of brightness  
 Parallax: Co-axial design

##### Deflection unit

Field of view (vertical/horizontal): 300° / 360°  
 Step size (vertical/horizontal): 0.009° (40,960 3D-Pixel on 360°) / 0.009° (40,960 3D-Pixel on 360°)  
 Max. vertical scan speed: 5.820rpm or 97Hz

##### Laser (optical transmitter)

Laser class: Laser class 1  
 Wavelength: 1550nm  
 Beam divergence: Typical 0.19mrad (0.011°) (1/e, half angle)  
 Beam diameter at exit: Typical 2.25mm (1/e)

##### Data handling and control

Data storage: SD, SDHC™, SDXC™; 32GB card included  
 Scanner control: Via touchscreen display and WLAN  
 New WLAN access: Remote control, scan visualisation are possible on mobile devices with Flash®

##### Multi-Sensor

Dual axis compensator: Levels each scan: Accuracy 0.015°; Range ± 5°  
 Height sensor: Via an electronic barometer the height relative to a fixed point can be detected and added to a scan.  
 Compass<sup>4</sup>: The electronic compass gives the scan an orientation. A calibration feature is included.  
 GPS: Integrated GPS receiver

**CLASS 1  
LASER PRODUCT**

<sup>1</sup> Ranging error is defined as a systematic measurement error at around 10m and 25m, one sigma <sup>2</sup> Ranging noise is defined as a standard deviation of values about the best-fit plane for measurement speed of 122,000 points/sec. <sup>3</sup> A noise-compression algorithm may be activated thereby compressing raw data noise by a factor of 2 or 4. Subject to change without prior notice. <sup>4</sup> Ferromagnetic objects can disturb the earth magnetic field, and lead to inaccurate measurements



1x Edge mobile ScanArm system



## Edge ScanArm<sup>®</sup> HD

### FARO LASER LINE PROBE SPECIFICATIONS

**Accuracy:**  $\pm 25\mu\text{m}$  ( $\pm 0.0008''$ )  
**Repeatability:**  $25\mu\text{m}$ ,  $2\sigma$  (0.01")  
**Stand-off:** 115mm (4.5")  
**Depth of field:** 115mm (4.5")  
**Effective scan width:** Near field 80mm (3.1")  
Far field 150mm (5.9")

**Points per line:** 2,000 points/line  
**Minimum point spacing:**  $40\mu\text{m}$ , (0.0015")  
**Scan rate:** 280 frames/second,  
280fps x 2,000 points/line =  
560,000 points/sec  
**Laser:** Class 2M  
**Weight:** 485g (1.1lbs.)



1x Prime mobile Arm system



FARO® Prime

## Product specificaties

Meetbereik	Herhaalbaarheid <sup>1</sup>	Nauwkeurigheid <sup>2</sup>	Gewicht	
Assen	6	6	6	
Prime	1.8 m (6 ft.)	0.019 mm (0.0007 in.)	±0.027 mm (±0.0011 in.)	9.3 kg (20.5 lbs.)

2x coordinate measuring machines  
(Conditioned environment)



measuring range [mm]

X: 6000

Y: 1600

Z: 1800